Final presentation

Research on the mechanism of protein folding dynamics

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Research background

Importance of protein folding and misfolding

- Protein is essential in a wide range of fields.
	- Membrane protein paly a vital role in the inter-cellular substance exchange and communication
	- \circ Protein enzyme is the most efficient catalyst, maintaining gazillion of chemical reaction in live system
- Protein misfolding leads to many diseases:
	- Creutzfeldt-Jakob disease (CJD)
	- Type 2 diabetes
	- Many neurodegenerative diseases
- The sequence of peptide chain determine the final structure of protein completely
- The protein can fold to the native structure rapidly and precisely
- Levinthal's paradox 1 :

The protein with 100 peptides may misfold into a maximum of 3^{198} different conformations. Therefore, it would require a time longer than the age of the universe to arrive at its correct native conformation if protein random searched all the possible conformation.

Multi-scale modeling

Fundamentals

When we sample in NVT ensemble, the probability density follows the Boltzmann distribution:

$$
p\left(\mathbf{q}_a, \mathbf{q}_{a-}\right) = \frac{\exp\left[-\frac{U\left(\mathbf{q}_a, \mathbf{q}_{a-}\right)}{k_B T}\right]}{\int_{\Omega}\prod\limits_{i=1}^{3N_a}\mathrm{d}q_a^{(i)}\prod\limits_{j=1}^{3N_{a-}}\mathrm{d}q_{a-}^{(j)}\mathrm{exp}\left[-\frac{U\left(\mathbf{q}_a, \mathbf{q}_{a-}\right)}{k_B T}\right]}
$$

• We can write experimental observations in the form of ensemble average:

$$
\left\langle A \right\rangle=\int_{\Omega}\prod_{i=1}^{3N_{a}}\mathrm{d}q_{a}^{(i)}\prod_{j=1}^{3N_{a-}}\mathrm{d}q_{a-}^{(j)}A\left(\mathbf{q}_{a}\right)p\left(\mathbf{q}_{a},\mathbf{q}_{a-}\right)=\int_{\Omega_{a}}\prod_{i=1}^{3N_{a}}\mathrm{d}q_{a}^{(i)}A\left(\mathbf{q}_{a}\right)\int_{\Omega_{a-}}\prod_{j=1}^{3N_{a-}}\mathrm{d}q_{a-}^{(j)}p\left(\mathbf{q}_{a},\mathbf{q}_{a-}\right)\\\text{Zhenyu Wei, June 2021}\qquad \qquad 8\,|\,74
$$

• Now we define a marginal probability density:

$$
\bar{p}\left(\mathbf{q}_a\right)=\frac{\displaystyle\int_{\Omega_{a-}}\prod_{i=1}^{3N_a}\mathrm{d}q_{a-}^{(i)}\mathrm{exp}\left[-\frac{U\left(\mathbf{q}_a,\mathbf{q}_{a-}\right)}{k_BT}\right]}{\displaystyle\int_{\Omega}\prod_{i=1}^{3N_a}\mathrm{d}q_a^{(i)}\prod_{j=1}^{3N_{a-}}\mathrm{d}q_{a-}^{(j)}\mathrm{exp}\left[-\frac{U\left(\mathbf{q}_a,\mathbf{q}_{a-}\right)}{k_BT}\right]}=\frac{\mathrm{exp}\left[-\frac{F\left(\mathbf{q}_a\right)}{k_BT}\right]}{\displaystyle\int_{\Omega_{a}}\prod_{i=1}^{3N_a}\mathrm{d}q_a^{(i)}\mathrm{exp}\left[-\frac{F\left(\mathbf{q}_a\right)}{k_BT}\right]}
$$

• Then we can rewrite the ensemble average as:

$$
\left\langle A \right\rangle = \int_{\Omega_a} \prod_{i=1}^{3N_a} \mathrm{d} q_a^{(i)} A\left(\mathbf{q}_a\right) \bar{p}\left(\mathbf{q}_a\right)
$$

, where the DoFs of *a*− have been integrated out.

Implicit solvent model

• Implicit solvent model treat solvent as a continuum dielectrics.

Electrostatic background

Consider a electrostatic potential ϕ :

$$
\Delta G_{\text{ele}}=q\left[\phi-\phi_{\text{vac}}\right]
$$

Combine the definition of ϕ and Gauss Law, we give the **Poisson** equation:

$$
\nabla \cdot [\varepsilon_r \nabla \phi] = -\frac{\rho}{\varepsilon_0}
$$

• And its special case for spherically symmetric system:

$$
\frac{1}{r^2}\frac{\mathrm{d}}{\mathrm{d}r}\left[r^2\frac{\mathrm{d}\phi}{\mathrm{d}r}\right]=-\frac{\rho(r)}{\varepsilon_r\varepsilon_0}
$$

Consider mean-field theory and Debye-Huckle theory:

$$
\frac{1}{r^2}\frac{\mathrm{d}}{\mathrm{d}r}\left[r^2\frac{\mathrm{d}\phi}{\mathrm{d}r}\right]=-\frac{e_0}{\varepsilon_r\varepsilon_0}\sum_i^{N_i}z_ic_i^0\mathrm{exp}\left[-\frac{z_ie_0\phi(r)}{k_BT}\right]
$$

• This equation is refereed to as Poisson-Boltzmann Equation. In the limit of $k_{B}T \gg z_{i}e_{0}\phi(r)$, we have:

$$
\frac{1}{r^2}\frac{\mathrm{d}}{\mathrm{d}r}\left[r^2\frac{\mathrm{d}\phi}{\mathrm{d}r}\right]=-\frac{e_0}{\varepsilon_r\varepsilon_0}\sum_i^{N_i}z_ic_i^0\left[1-\frac{z_ie_0\phi(r)}{k_BT}\right]=-\left[\frac{e_0^2}{\varepsilon_r\varepsilon_0k_BT}\sum_i^{N_i}z_i^2c_i^0\right]\phi(r)
$$

, which is called Linearized Poisson-Boltzmann Equation.

Generalized Born Model

Still et al $^{[1]}$ invent Generalized Born Model follows:

$$
G_\mathrm{ele} = \frac{1}{2\varepsilon}\sum_{i=1}^{N_c}\sum_{j=1,j\neq i}^{N_c}\frac{q_iq_j}{r_{ij}} - \frac{1}{2}\left(1-\frac{1}{\varepsilon}\right)\sum_{i=1}^{N_c}\frac{q_i^2}{R_i}
$$

• This equation can be rearranged as:

$$
G_{\text{ele}} = \frac{1}{2} \sum_{i=1}^{N_c} \sum_{j=1, j \neq i}^{N_c} \frac{q_i q_j}{r_{ij}} - \frac{1}{2} \left(1 - \frac{1}{\varepsilon} \right) \sum_{i=1}^{N_c} \sum_{j=1, j \neq i}^{N_c} \frac{q_i q_j}{r_{ij}} - \frac{1}{2} \left(1 - \frac{1}{\varepsilon} \right) \sum_{i=1}^{N_c} \frac{q_i^2}{R_i}
$$

[1]: W Clark Still, Anna Tempczyk, Ronald C Hawley, and Thomas Hendrickson. Semianalytical treatment of solvation for molecular

mechanics anddynamics.Journal of the American Chemical Society, 112(16):6127–6129, 1990

As $\Delta G_{\text{ele}}=q\left[\phi-\phi_{\text{vac}}\right]$, we have:

$$
\Delta G_{\mathrm{ele}} = -\frac{1}{2}\left(1-\frac{1}{\varepsilon}\right)\sum_{i=1}^{N_c}\sum_{j=1}^{N_c}\frac{q_iq_j}{f_{GB}}
$$

, where f_{GB} stands for the combination of last two terms. As this expression is similar to the Born energy, the model is refereed to as generalized Born model. And Still states that:

$$
f_{GB}=\sqrt{r_{ij}^2+R_iR_j\mathrm{exp}\left[-\frac{r_{ij}^2}{\gamma R_iR_j}\right]}
$$

Consider a two dielectric model shown below:

• This model is spherically symmetric, describing several charges $\boldsymbol{\epsilon}$ mbedded in a dielectric with **low permittivity** ε_{in} which is surrounded by a different dielectric with **higher permittivity** $\varepsilon_{\rm out}$

• For such a discrete distributed charge system, we can rewrite Poisson equation with Green function:

$$
\nabla^2\mathbf{G}\left(\mathbf{r}_i,\mathbf{r}_j\right)=-\frac{\delta\left(\mathbf{r}_i-\mathbf{r}_j\right)}{\varepsilon_{\text{in}}\varepsilon_0}
$$

, solution of which has the form:

$$
\mathbf{G}\left(\mathbf{r}_{i},\mathbf{r}_{j}\right)=\frac{1}{4\pi\varepsilon_{\text{in}}\varepsilon_{0}}\frac{1}{||\mathbf{r}_{i}-\mathbf{r}_{j}||}+\mathbf{F}\left(\mathbf{r}_{i},\mathbf{r}_{j}\right)
$$

Obviously, $\mathbf{F}\left(\mathbf{r}_{i}, \mathbf{r}_{j}\right)$ stands for the complex solute-solvent interaction:

$$
\Delta G_{\mathrm{ele}}=\frac{1}{2}\sum_{i=1}^{N_{c}}\sum_{j=1}^{N_{c}}\mathbf{F}\left(\mathbf{r}_{i},\mathbf{r}_{j}\right)q_{i}q_{j}
$$

Analytical solution of Poisson Equation for this model exists $^{\lbrack 1]}$:

$$
\mathbf{F}\left(\mathbf{r}_{i},\mathbf{r}_{i}\right)=-\frac{1}{A}\left(\frac{1}{\varepsilon_{\text{in}}}-\frac{1}{\varepsilon_{\text{out}}}\right)\sum_{n=0}^{\infty}\frac{t_{ii}^{n}}{1+\frac{n}{n+1}\beta} \\\mathbf{F}\left(\mathbf{r}_{i},\mathbf{r}_{j}\right)=-\frac{1}{A}\left(\frac{1}{\varepsilon_{\text{in}}}-\frac{1}{\varepsilon_{\text{out}}}\right)\sum_{n=0}^{\infty}\frac{t_{ij}P_{n}(cos\theta)}{1+\frac{n}{n+1}\beta}
$$

, where $t_{ij} = r_i r_j / A^2$, $\beta = \varepsilon_{in}/\varepsilon_{out}$, and $P_n(cos\theta)$ are associated Legendre functions.

[1]: John G Kirkwood. Theory of Solutions of Molecules Containing Widely Separated Charges with Special Application to Zwitterions. The

Journal of Chemical Physics, 2(7):351–361, 1934.

First we consider the solution of $\mathbf{F}\left(\mathbf{r}_i,\mathbf{r}_i\right)$. In the limit of $\beta\rightarrow0$:

$$
\Delta G_{\text{ele}}^{ii}=\frac{q_i^2}{2}\textbf{F}\left(\textbf{r}_i, \textbf{r}_i\right)=-\frac{1}{2}\left(\frac{1}{\varepsilon_{\text{in}}}-\frac{1}{\varepsilon_{\text{out}}}\right)\frac{q_i^2}{A(1-t_{ii})}=-\frac{1}{2}\left(\frac{1}{\varepsilon_{\text{in}}}-\frac{1}{\varepsilon_{\text{out}}}\right)\frac{q_i^2}{A-\frac{r_i^2}{A}}
$$

As the final result is similar to the Born energy, we name the denominator $R_i = A - r_i^2/A$ after **effective Born radius**.

 ${\sf Next}$ consider ${\bf F}\left({\bf r}_i,{\bf r}_j\right)$, we first replace $n/(n+1)$ with a constant α , for all $n\geq 1$, rewriting the series as:

$$
1 + \frac{1}{1 + \alpha \beta} - \frac{1}{1 + \alpha \beta} + \sum_{n=1}^{\infty} \frac{t_{ij}^n P_n(\cos \theta)}{1 + \alpha \beta} = \frac{1}{1 + \alpha \beta} \left[\sum_{n=0}^{\infty} \left[\frac{t_{ij}^n P_n(\cos \theta)}{1 + \alpha \beta} \right] + \alpha \beta \right]
$$

• , where $\sum_{n=0}^{\infty} t^n P_n(\cos \theta)$ can be simplified as $1/\sqrt{1 - 2t_{ij}\cos \theta + t_{ij}^2}$:

$$
\Delta G_{\text{ele}}^{ij} = \frac{q_i q_j}{2} \mathbf{F}(\mathbf{r}_i, \mathbf{r}_i) = -\frac{1}{2} \left(\frac{1}{\varepsilon_{\text{in}}} - \frac{1}{\varepsilon_{\text{out}}} \right) \frac{q_i q_j}{1 + \alpha \beta} \left[\frac{1}{\sqrt{r_{ij}^2 + R_i R_j}} + \frac{\alpha \beta}{A} \right]
$$

- , which yields
$$
f_{GB}=\sqrt{r_{ij}^2+R_iR_j}
$$

• Now we need to estimate the effective Born radius. In classical electrostatic:

$$
G_\text{ele} = \frac{1}{2}\int_\Omega \rho \phi dV = \frac{1}{8\pi}\int_\Omega \mathbf{E}\cdot \mathbf{D} dV
$$

Then we introduce a essential approximation, which state $\mathbf D$ has the same form as Coulomb field $\mathbf{D}_i \approx \frac{q_i}{r^2} \hat{\mathbf{r}}_i$:

$$
G_{\text{ele}}^{ii}=\frac{1}{8\pi}\left[\int_{\Omega_{\text{in}}}\frac{q_iq_i}{\varepsilon_{\text{in}}r^4}dV+\int_{\Omega_{\text{out}}}\frac{q_iq_i}{\varepsilon_{\text{out}}r^4}dV\right]\\ \Delta G_{\text{ele}}^{ii}=G_{ii}-\frac{1}{8\pi}\int_{\Omega}\frac{q_i^2}{\varepsilon_{\text{in}}r^4}dV=-\frac{1}{8\pi}\left(\frac{1}{\varepsilon_{\text{in}}}-\frac{1}{\varepsilon_{\text{out}}}\right)\int_{\Omega_{\text{out}}}\frac{q_i^2}{r^4}dV
$$

Recall the expression of $\Delta G_{\rm ele}^{ii}$, we have:

$$
\frac{1}{R_i}=\frac{1}{4\pi}\int_{\Omega_{\rm out}}\frac{1}{r^4}dV
$$

As the boundary of $\Omega_{\rm in}$ is usually complex, we rewrite $\Delta G_{\rm ele}^{ii}$ as:

$$
\frac{1}{R_i}=\frac{1}{4\pi}\left[\int_0^k\frac{1}{r^2}4\pi r^2dr-\int_{\Omega_{\rm in}-\Omega_s}\frac{1}{r^4}dV\right]=\frac{1}{k}-\frac{1}{4\pi}\int_{\Omega_{\rm in}-\Omega_s}\frac{1}{r^4}dV
$$

, where Ω_s is a sphere volume with radius $k.$

Finally we can consider the influence of mobile ion based on the Debye-Huckle theory by replacement:

$$
\left(\frac{1}{\varepsilon_{\text{in}}}-\frac{1}{\varepsilon_{\text{out}}}\right)\rightarrow\left(\frac{1}{\varepsilon_{\text{in}}}-\frac{\exp\left[-\kappa f_{GB}\right]}{\varepsilon_{\text{out}}}\right)
$$

, where κ is the Debye screening radius:

$$
\kappa = \frac{e_0^2}{\varepsilon_r \varepsilon_0 k_B T} \sum_i^{N_i} z_i^2 c_i^0
$$

Enhanced sampling

Fundamentals

• Consider a mapping:

 $\theta: \Omega \in \mathbb{R}^{3N} \to \Theta \in \mathbb{R}^n, n \ll 3N$

Then we can analyze free energy based on the distribution of θ :

 $F\left(\theta^{\prime}\right)=-k_{B}T\ln\left[H\left(\theta^{\prime}\right)\right]$

- Advantages:
	- Sampling as a $3N-n$ dimensional hyper-sphere with high efficiency;
	- \circ It's easier to manipulate CV, overcoming the energy barrier;

 \circ It's easier to compare to the experimental observations;

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Umbrella sampling

• In simulation, PDF can be derived from histogram on collective variables. However, the estimation on the rare events is accompanied with high statistical error

Simulation with bias potential:

$$
\tilde{U}(\mathbf{R})=U(\mathbf{R})+\Delta U(\mathbf{R})
$$

where three terms corresponds to new potential, origin potential and bias potential, respectively.

• So we have:

$$
\begin{array}{lcl} \tilde{F}(\xi') & = & -k_B T ln \left(\frac{1}{Z} \int d^{3N} R e^{-\beta U({\bf R})} e^{-\beta \Delta U({\bf R})} \delta \left(\xi({\bf R}) - \xi' \right) \right) \\ \\ & = & F(\xi') + \Delta U(\xi') + C \end{array}
$$

Usually, a potential like harmonic oscillator is a good choice:

$$
\Delta U({\bf R}) = \frac{1}{2}~\mathrm{K}_{bias}~\left(\xi({\bf R})-\xi_0\right)^2
$$

where K_{bias} and ξ_0 are two hyper parameters for umbrella sampling

- Suppose we perform a series of simulation over different bias potential
- Each histogram is overlapped with others (like umbrella)
- We can reconstruct the free energy with a series curve with little error

Weighted Histogram Analysis Method

- Initial data:
	- A collective variable *ξ* : Ω → Ξ ∈ R *d* , *d* ≪ 6*N*
	- M independent trajectories (usually with a biased potential), $\,$ $S_i, i \in [1, M]$
	- \circ The histogram and probability distribution (or probability density) of each trajectories on reaction coordinate: $h_i(\xi')$ and $p_i(\xi'),\ i\in\mathbb{Z}$ $[1, M]$
- Final goal:
	- The probability distribution (or probability density) on reaction \bigcirc coordinate of unbiased simulation

Initial Assumption: the biased probability distribution $p_i(\xi')$ is related to the unbiased one $p_0(\xi')$:

$$
p_i(\xi')=f_ic_i(\xi')p_0(\xi')
$$

where $c_i(\xi')$ is the biasing factor corresponds to the influence of bias potential:

$$
\begin{array}{l} \circ \;\; c_i(\xi') = exp\left[-(\beta_i - \beta_0)E_0(\xi')\right] \text{for temperature biasing} \\ \circ \;\; c_i(\xi') = exp\left[-\beta \Delta U(\xi')\right] \text{for coordinate biasing} \end{array}
$$

And f_i is a normalization factor:

$$
f_i^{-1} = \int_{\Xi} c_i(\xi') p_0(\xi') d\xi'
$$

\n
$$
= \int_{\Xi} e^{-\beta \Delta U(\xi')} \frac{1}{Q_0} \int_{\Omega} e^{-\beta U(\mathbf{q})} \delta [\xi(\mathbf{q}) - \xi] d\mathbf{q} d\xi
$$

\n
$$
= \frac{1}{Q_0} \int_{\Xi} \int_{\Omega} e^{-\beta [U(\mathbf{q}) + \Delta U(\mathbf{q})]} \delta [\xi(\mathbf{q}) - \xi] d\mathbf{q} d\xi
$$

\n
$$
= \frac{1}{Q_0} \int_{\Omega} e^{-\beta [U(\mathbf{q}) + \Delta U(\mathbf{q})]} d\mathbf{q} = \frac{Q_i}{Q_0}
$$

As we know:

$$
\Delta A_{ij}=-k_B T ln \frac{Q_j}{Q_i}=-k_B T ln \frac{\int_{\Gamma_j} exp\left[-\frac{U_j(\mathbf{q})}{k_B T}\right] d\mathbf{q}}{\int_{\Gamma_i} exp\left[-\frac{U_i(\mathbf{q})}{k_B T}\right] d\mathbf{q}}
$$

• So we have:

$$
\beta^{-1}ln f_i = \Delta A_{0i}
$$

• Based on the initial assumption:

$$
p_i(\xi')=f_ic_i(\xi')p_0(\xi')
$$

We can define the estimation of unbiased result from i trajectory: $\overline{}$

$$
p_0^{(i)}(\xi') = \frac{p_i(\xi)}{f_i c_i(\xi')} = \frac{h(\xi')}{N_i f_i c_i(\xi')}
$$

where $h(\xi')$ is the histogram value and N_i is the total samples of trajectory $i.$

And we give the final estimation of $p_0(\xi')$ as a weighted average:

$$
p_0^{est}(\xi') = \sum_{i=1}^M w_i p_0^{(i)}(\xi')
$$

- Obviously, w_i satisfy the normalization condition: $\sum w_i = 1.$ *i*=1 *M*
- Clearly, if we want to get a good estimation, we want the variance of each data point to be the minimum:

 $var(p_0^{est}(\xi')) \quad = \quad \big\langle (p_0^{est}(\xi') - \langle p_0^{est}(\xi') \rangle)^2 \big\rangle$ $_{0}^{est}(\xi^{\prime})\rangle)^{2}\big\rangle$

$$
\begin{array}{lcl} = & \displaystyle \Bigg\langle\Bigg(\displaystyle\sum_{i=1}^{M}w_{i}p_{0}^{(i)}(\xi')-\bigg\langle\displaystyle\sum_{i=1}^{M}w_{i}p_{0}^{(i)}(\xi')\bigg\rangle\Bigg)^{2}\Bigg\rangle \\ \\ = & \displaystyle \Bigg\langle\Bigg(\displaystyle\sum_{i=1}^{M}w_{i}\left(p_{0}^{(i)}(\xi')-\Big\langle p_{0}^{(i)}(\xi')\Big\rangle\Big)\Bigg)^{2}\Bigg\rangle \end{array}
$$

$$
\begin{array}{l} \textrm{We define } \delta p_0^{(i)}(\xi') = \left(p_0^{(i)}(\xi') - \left\langle p_0^{(i)}(\xi') \right\rangle \right). \textrm{ Then we have: } \\ \displaystyle var\left(p_0^{est}(\xi') \right) \end{array}
$$

$$
=\left.\,\left\langle \sum_{i=1}^M w_i^2 ({\delta p}_0^{(i)}(\xi'))^2+\sum_{j=1}^M\sum_{k!=j}^M w_j w_k {\delta p}_0^{(j)}(\xi')\cdot {\delta p}_0^{(k)}(\xi')\right\rangle\right.
$$

$$
~=~ \sum_{i=1}^M w_i^2 \left< \left(\delta p_0^{(i)}(\xi')\right)^2\right> + \sum_{j=1}^M \sum_{k! = j}^M w_j w_k \left< \delta p_0^{(j)}(\xi')\cdot \delta p_0^{(k)}(\xi')\right>
$$

Always, we can make the assumption of independent sampled trajectory, which means $\left< \delta p_0^{(j)}(\xi') \cdot \delta p_0^{(k)}(\xi') \right> = 0$ and we have $\Big\langle\left(\,\delta p_0^{(i)}(\xi')\right)^2\,\Big\rangle=var\left(\,p_0^{(i)}(\xi')\right)$, so we can rewrite equation as: $\binom{(k)}{0}$ $\left(\xi'\right)\Big\rangle = 0$ 2 $\Big\rangle=var\left(p_0^{(i)}(\xi')\right)$,

$$
var\left(p_0^{est}(\xi')\right)=\sum_{i=1}^M w_i^2 var\left(p_0^i(\xi')\right)
$$

As we know $var(ax)=\langle a^2x^2\rangle-\langle ax\rangle^2=a^2var(x)$, so recall the definition of $p_0^{(i)}(\xi') = \frac{P^{(i)}(s)}{P^{(i)}(s)} = \frac{P^{(i)}(s)}{N! \cdot P^{(i)}(s)}$, we have: $var\left(p_0^{est}(\xi')\right) = 0$ *i*=1 \sum – *M* $N_i^2c_i^2(\xi)f_i$ *i* 2 *i* 2 $w_i^2var\left(h(\xi)\right)^2$ $var(ax) = \left\langle a^{2}x^{2}\right\rangle - \left\langle ax\right\rangle ^{2} = a^{2}var(x)$ $p_0^{(i)}(\xi') = \frac{p_i(\xi)}{f_i g_i(\xi')} = 0$ $f_ic_i(\xi')$ $p_i(\boldsymbol{\xi})$ $N_i f_i c_i(\xi')$ $h(\xi')$
- If we have N independent samples, the probability and variance of having n counts in one bin will follow the $\bm{{\mathsf{binomial}}}\$ distribution
	- Mean: *npi*(*ξ*) ′
	- $\textsf{Variance:}~np_i(\xi')(1-p_i(\xi'))$
- In the limit of large N and small $p_i(\xi')$ (exactly what happened for a long simulation and a detailed histogram), the binomial distribution can be treated as a Poisson distribution:

$$
P(n)=exp(-Np_i(\xi'))\frac{(Np_i(\xi'))^n}{n!}
$$

Means and variance: $Np_i(\xi')$

• Substituting the variance so we have:

$$
var\left(p_0^{est}(\xi')\right) = \sum_{i=1}^{M} \frac{w_i^2 N_i f_i c_i(\xi') p_0(\xi')}{N_i^2 c_i^2(\xi) f_i^2} = \sum_{i=1}^{M} \frac{w_i^2 p_0(\xi')}{N_i c_i(\xi) f_i}
$$

We want to minimize equation with the constraint
$$
\sum_{i=1}^{M} w_i = 1
$$
, so we

define a Lagrange multiplier λ , giving a goal function:

$$
G=\sum_{i=1}^M \frac{w_i^2p_0(\xi')}{N_ic_i(\xi)f_i}+\lambda \sum_{i=1}^M w_i
$$

To minimize the goal function, first take the partial derivative:

$$
\frac{\partial G}{\partial w_i} = \frac{2w_i p_0(\xi')}{N_i c_i(\xi')f_i} + \lambda
$$

• And setting it to zero, obtain:

$$
w_i=-\frac{N_i c_i(\xi')f_i}{2p_0(\xi')}\lambda
$$

• Substitute to the constraints:

$$
\sum_{i=1}^M -\frac{N_i c_i(\xi')f_i}{2p_0(\xi')}\lambda=1
$$

so we have:

$$
\lambda = -\frac{2p_0(\xi')}{\sum_{i=1}^M N_i c_i(\xi') f_i}
$$

• and obtain the weight:

$$
w_i = \frac{N_i c_i(\xi') f_i}{\sum_{i=1}^M N_i c_i(\xi') f_i}
$$

Substitute this weight and finally we get:

$$
p_0^{est}(\xi') = \sum_{i=1}^M w_i \frac{h(\xi')}{N_i f_i c_i(\xi')} = \frac{\sum_{i=1}^M h_i(\xi')}{\sum_{i=1}^M N_i f_i c_i(\xi')}
$$

This equation and the normalization condition:

$$
f_i^{-1}=\int_{\Xi}c_i(\xi')p_0^{est}(\xi')\ d\xi'
$$

are collectively known as the Weighted Histogram Analysis Method (WHAM) equations.

Free energy of ion interaction in solution

Model detail

- Simulation tool: OpenMM
- Number of atoms: 2072
- Thermostat: Andersen Thermostat
- Barostat: MonteCarlo Barostat
- Time step: 1 femtosecond
- Equilibrium temperature: 300K
- Equilibrium pressure: 1 Bar

Umbrella sampling settings

- 10 replicas
- Each has 200 trajectories
- Each run for 200ns
- Each executed for 10 hours

SCHM Result

MDAnalyser Demo

from mdanalyser.analyser import WHAMUmbrellaSamplingAnalyser

```
path current = sys.path[0]path_out_cv = path_current + '/../output/cv_files'
```
analyzer = WHAMUmbrellaSamplingAnalyser()

```
analyzer.setDirPath(path_out_cv)
analyzer.setFileIdRangeFromStartToEnd(0, 99)
analyzer.setBinRangeFromStartToEnd(1, 15, 250)
analyzer.setConstantK(100)
analyzer.setTemperature(300)
```

```
analyzer.loadData()
analyzer.iterativeSolver(num_steps=500)
```
Validation:

Quickly convergence

Sensitive to the constant *K* of harmonic oscillator bias potential

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• Better performance than Self-Consistent Histogram Method (SCHM) in sparse sampling part

Free energy matrix

Model details

- Two amino acid
- number of atoms: around 5000
- NaCl concentration: 0.15mol/L
- time step: 1 fs
- thermostat: Langevin
- barostat: MonteCarlo 1bar
- integrator: Langevin Integrator
- forcefield: 'amber14/tip3pfb.xml'

Collective variable details

• Defination:

The distance between the centroid center of two amino acid

$$
\Delta U = \frac{1}{2} K (\mathbf{c}_{dist} - \mathbf{c}_0)^2, \ \mathbf{c}_{dist} = \frac{1}{M_{tot}} \sum_{i=1}^N m_i \mathbf{q}_i
$$

$$
F_{x_i} = \frac{\partial \Delta U}{\partial c_{dist,x}} \frac{\partial c_{dist,x}}{\partial x_i} = \frac{m_i}{M_{tot}} K c_{dist,x}
$$

Range: *r* ∈ [1, 20]*A*

Grid: 200 trajectories: 150 \in $[1, 15)$, 50 \in $[10, 20)$

Pdff-distribute

Result

Sort by molecular weight

OpenPD

Coarse-Grained Model

The protein is treated as a peptides chain, each of which consists two beads:

- CA bead represents the backbone part of the peptide;
- SC bead represents the side chain part of the peptide;

Force field expression

$$
U_{tot} \quad = \quad U_{Non-Bonded} + U_{Bond} + U_{Torsion}
$$

$$
=\,\,\sum_{i=1}^{N_{A}}\sum_{j=i+1}^{N_{A}}U_{Non-Bonded}^{(ij)}\left(\mathbf{r}_{ij}\right)\,+\sum_{i=1}^{N_{B}}U_{Bond}^{(i)}\left(l_{i}\right)\,+\,\sum_{i=1}^{N_{T}}U_{Torsion}^{(i)}\left(\theta_{i}\right)
$$

- $U_{Non-Bonded}$ describes the interaction between **SC** and **SC** (no neighbor) bead.
- U_{Bond} describes the bond that constraint the connected bead.
- $U_{Torsion}$ describes the torsion angle preference between neighbor ${\bf SC}$ bead.

Computational detail

- Non bonded interaction:
	- \circ CV: the distance between centroid of two peptides' side chain;
	- Sampling algorithm: Umbrella sampling; 500ns;
- Bond interaction:
	- CV: the distance between two target beads;
	- Sampling algorithm: Umbrella sampling; 500ns;
- Torsion interaction:

 $\mathsf{CV}{:}\, {}^2\angle SC-CA-CA-SC;$

○ Sampling algorithm: Well-tempered Metadynamics; 200ns;

Non Bonded Result

Torsion Result

Difference from ordinary coarse grained force field

- PDFF does not contain solvent term;
- PDFF is not fitting from experimental data or other result;
- PDFF is, theoretically, generalized enough for all protein, no matter whether exists homologous pair in the database

Overview

OpenPD, standing for Open Peptide Dynamics, is a python package, distributed freely under the terms of GPLv3, for peptide dynamics simulation.

- <https://github.com/openpd-dev/openpd>
- https://openpd.net

Extensible packages

- openpd.loader package:
	- PDBLoader, SequenceLoader
- openpd.force package:
	- PDFFNonBondedForce, PDFFBondForce, PDFFTorsionForce
- openpd.integrator package:
	- VerletIntegrator, VelocityVerletIntegrator, BrownianIntegrator ...
- openpd.dumper package:

LogDumper, SnapshotDumper, PDBDumper, XYZDumper

Current Planed

Demo Code

```
1 import openpd as pd
2 from openpd.unit import \star\overline{3}4 system = pd. SequenceLoader('data/simulation.json').createSystem()
5 ensemble = pd. ForceEncoder(system).createEnsemble()
6 integrator = pd.VelocityVerletIntegration(1*femtosecond, 300*kelvin)simulation = pd.Simulation(ensemble, integration)7
8
9 log_dumper = pd. LogDumper(
       'simulation.log', 50, get_potential_energy=True, get_temperature=True,
10
11get_steps=True, get_elapsed_time=True, get_remain_time=True
12)13 snapshot_dumper = pd.SnapshotDumper('simulation.pds', 50)
14 xyz_dumper = pd.XYZDumper('simulation.xyz', 50)
15 simulation.addDumpers(log_dumper, snapshot_dumper, xyz_dumper)
16
17 simulation.minimizeEnergy('gd', max_iteration=20)
18 simulation.step(50000)
```
Result

Discussion

Non-Bonded interaction only considered the SC bead;

The constraint on CA bead is completely locally:

- Neglect the interaction of distance between CA and non-neighbored SC;
- Neglect the interaction of distance between CA and non-neighbored CA;

Future proposal

- Implicit solvent
	- Machine learning solver for PE, PBE, LPBE
	- Solvent boundary potential for arbitrary boundary
- Coarse grained model
	- Refinement of PDFF
- Research large functional proteins
	- DNA polymerase \bigcirc

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Questions & Answers